Akashi College				Year 2023			C	ourse Dynamics of Machinery			
Course Information											
Course Code 5436					Course Catego	ry	Specializ	ed / Compulsory			
Class Forr	nat	Lecture				Credits		Academi	c Credit: 2		
Departme	ent	Mechan	ical E	ngineering		Student Grade		4th			
Term	Term First Seme			er	Classes per We	ek	2				
Textbook and/or Teaching Materials					•						
Instructor	Instructor SEKIMORI Daisuke										
Course	Course Objectives										
<ol> <li>(1) Can consider the vibratory system of one and two degrees of freedom based on the equations of motion.</li> <li>(2) Can find the equations of motion (linear second-level differential equations) against the basic vibration model and understand what kind of physical phenomena the solution represents.</li> <li>(3) Learn the modeling methods and sensibility, or the analysis process, which are essential for the analysis process.</li> <li>(4) Can acquire the ability to apply the knowledge they have learned to reduce and prevent vibration and about measurement and instrumentation of vibration, and respond appropriately.</li> </ol>											
Rubric											
			Ic	leal Level		Standard Level			Unacceptable Level		
Achievement 1				an accurately bration syster vo degrees of n the equatior	examine the m with one and freedom based as of motion.	Can examine the vibration system with one and two degrees of freedom based on the equations of motion.			Cannot examine the vibration system with one and two degrees of freedom based on the equations of motion.		
Achievement 2				Can find the equations of motion. The equations of motion. Can find the equations of motion (linear second-level differential equations) against the basic vibration model and fully understand what kind of physical phenomena the solution represents			uation second ations) tion mo d what mena t ents.	s of Cannot find what kind of level physical phenomena the against solution is represented by del and leading the equations of motion kind of (linear second-level differential he equations) to the basic vibratior model.			
Achievem	ent 3		A te m pi th	ccurately learn echniques, the nodeling, or the rocess that ar ne analysis pro	n the modeling e sense of le analysis e essential for ocess.	ling Learn the modelin the sense of mode analysis process t for essential for the a process.		echniques 3, or the are /sis	Do not learn the modeling methods and sense of analysis, or the process of analysis, which is essential to the progress of analysis.		
			Ci th le vi m in ar	an acquire the le knowledge arned to redu bration and a leasurement a strumentation nd respond ap	Can acquire the ability to apply the knowledge they have learned to reduce and prevent vibration and about measurement and instrumentation of vibration, and respond appropriately.		y to apply ave I prevent pration, ately.	Cannot acquire the ability to apply the knowledge they have learned to reduce and prevent vibration and about measurement and instrumentation of vibration, and respond appropriately.			
Assigne	d Depar	tment Ol	bjec	tives							
Teachin	a Metho	d									
Outline Identifying second tw second-lew phenomen			ing th to stu I two Ievel iena 1	g the dynamic behavior (vibration) of a machine is essential in the design of a machine. In this study the basics of mechanical vibration analysis, students will examine the vibration system with wo degrees of freedom based on the motion equation. Derive the equations of motion (linear vel differential equations) against the basic vibration model and consider what kind of physical na the solution represents.							
Style Lee		Lectures	ctures will be given in line with the textbook, and practice problems will be assigned.								
Notice This course's content will amount to 90 hours of study in total. These hours include the learning time guaranteed in classes and the standard self-study time required for pre-study / review, and completing assignment reports. Since this is one of the few courses in mechanical engineering on dynamics, studen requested to fully learn the basic idea. It is also important to review the knowledge gained in basic subject as Maths III A, Maths III B, and Industrial Dynamics I. Students who miss 1/3 or more of classes will not be eligible for evaluation.								include the learning time dy / review, and completing neering on dynamics, students are owledge gained in basic subjects			
Charact	eristics o	of Class /	/ Div	ision in Lea	arning						
Active Learning			□ Aided by ICT		Applicable to Remo		ote Class	<ul> <li>Instructor Professionally Experienced</li> </ul>			
Course	Plan	1	<u> </u>				-				
			Iher	me		Goals					
1st Semeste r	1st Quarter	1st	Basics of vibration			Learn basic know mathematics new vibration phenor			vieage of mechanics and cessary for the analysis of nena.		
		2nd	Deg	rees of freedo	of motion	Understand the concept of degrees of freedom. Understand the basics of how to derive the equations of motion based on the Newton's second law.					
		3rd	Non- free	-damping free dom (1)	e vibration of one	degree of	Learn how to derive equations of motion for non- damping free-vibration systems such as linear and rotational vibration can be studied. Also, understand how to derive the equations of motion in systems that contain multiple springs, plate springs, etc.				

		4th		Non-damping free oscillation with one degree of freedom (2)				Can standardize the equations of motion of the non-damping free-vibration system and learn the solutions. Understand the behavior of the system and its natural frequencies.				
			5th	Damped free freedom (1)	oscill	ation with one de	Understand the principle of dash pot, the damping element . Learn how to derive the equations of motion for damping free-vibration systems such as linear and rotational vibrations can be studied.					
			6th	Damped free oscillation with one degree of reedom (2)				Can standardize the equations of motion for the damping free-vibration system and learn the solutions. Understand the relationship between damping ratio and system behavior.				
			7th	Fransient vibration				Understand the transient response of the oscillation system, which is subjected to step-function and impulse-function forces from the outside.				
			8th	Midterm exan								
			9th	One degree of freedom damping force vibration (1)				Learn how to derive the equations of motions for damping force vibration systems such as linear and rotational vibrations.				
			10th	One degree of freedom for damping force vibration (2)				Can standardize the equations of motion of the damping force vibration system and learn the solutions. Understand the frequency response of the system and the forces transmitted to the foundation.				
2r Qi			11th	One degree of freedom for damping force vibration (3)				Learn how to derive and solve the motion equation of the damping force vibration system by enforced displacement. Understand the principle of a vibration meter, which is an application of the system.				
	2nd Quarte	er	12th	2 degrees of freedom vibration (1)				Understand the concept of coupled vibration by finding the equations of simultaneous motion in models with two degrees of freedom, such as linear and rotational vibration.				
			13th	2 degrees of freedom vibration (2)				Learn how to solve the equations of motion of coupled free vibration. Understand the reference frequencies and modes that obtained from the frequency equations.				
			14th	Force vibratio	orce vibration of two degrees of freedom				Learn how to derive and solve for the equations of motion for coupled forced vibration. Understand the frequency response of a system.			
			15th	Vibration isola	ibration isolation and vibration control				Learn the principle of a dynamic damper consisting of mass and spring, and can examine the reduction and prevention of vibration.			
			16th	Final exam								
Evaluat	ion Me	1ethod and Weight (%)									1	
		Examination		Presentatio	on	Mutual Evaluations between students	Behavior	Portfolio		Exercises	Total	
Subtotal		90		0		0	0	0		10	100	
Basic Proficiency		0		0		0	0	0		0	0	
Specialized Proficiency		90		0		0	0	0		10	100	
Cross Area Proficiency		0		0		0	0	0		0	0	