| Tsuyama College      |                         |                                  | Year   | ar 2020       |  |              | Course<br>Title   | Advanced Controls<br>Engineering |  |  |  |
|----------------------|-------------------------|----------------------------------|--|---------------|--|--------------|---|----------------------------------|--|--|--|
| Course 2             | Informat                | tion                             |  |               |  |              |   |                                  |  |  |  |
| Course Co            | ode                     | 0149                             | 49   |               |  | gory         | Specializ   | tive                             |  |  |  |
| Class Forr           | nat                     | Lecture                          | Lecture  |               |  |              | Academic Credit: 2  |                                  |  |  |  |
| Department           |                         | Technolo                         | ent of Integrated<br>ogy Communicatio<br>tions System Proc   | on and        | Student Grad                                     | de           | 5th   |                                  |  |  |  |
| Term                 |                         | Year-rou                         | , <u> </u>   | Classes per V | Classes per Week 1                               |              |   |                                  |  |  |  |
| Textbook<br>Teaching |                         | Textbool                         | ks : "Wakariyasui Gendai Seigyo Riron" Mori, (Morikita Syuppan)  |               |  |              |   |                                  |  |  |  |
| Instructor           | -                       | YAGI Hid                         | deyuki   |               |  |              |   |                                  |  |  |  |
| Course               | Objectiv                | es                               |  |               |  |              |   |                                  |  |  |  |
| The purpo            | piectives :             | quire appli                      | ·  | ed to automa  | tic control theory.                              |              |   |                                  |  |  |  |
| 2. To und            | erstand PI<br>erstand m | D control t<br>odern cont        | neory.<br>rol theory.  |               |  |              |   |                                  |  |  |  |
| Rubric               |                         |                                  | ,  |               |  |              |   |                                  |  |  |  |
|                      |                         | Fxce                             | Excellent  |               | Good Act   |              | cceptable   |                                  | Not acceptable   |  |  |
| Achievem             | Achievement 1           |                                  | The student can apply<br>PID control theory to   |               | The student can<br>understand the theory of      |              | The student can<br>understand the basic<br>theory of PID control. |                                  | The student will not try<br>to understand the basic<br>theory of PID control.    |  |  |
| Achievement 2        |                         | The                              | The student can apply The stu<br>modern control theory to unders   |               | dent can<br>and the theory of<br>control theory. | The stunders | tudent can<br>stand the basic                                     |                                  | The student will not try<br>to understand the basic<br>theory of modern control. |  |  |
| Assigne              | d Denar                 | tment Ob                         |  | modern        | 2.5.1.6. of theory i                             | / CO1 y      | J. modern   |                                  | Tanger, et modern condon   |  |  |
|                      |                         |                                  | Jeenves  |               |  |              |   |                                  |  |  |  |
| Teachin              | g Metho                 |                                  |  |               |  |              |   |                                  |  |  |  |
| Outline              |                         | Required<br>Foundati<br>engineer | General or Specialized : Specialized<br>Required, Elective, etc. : Elective subjects<br>Foundational academic disciplines : Engineering / Electrical and electronic engineering / Control and system<br>engineering  |               |  |              |   |                                  |  |  |  |
|                      |                         | This clas                        | Relationship with Educational Objectives :<br>This class is equivalent to "(2) Acquire basic science and technical knowledge".   |               |  |              |   |                                  |  |  |  |
|                      |                         | The main                         | Relationship with JABEE programs :<br>The main goals of learning / education in this class are "(A), A-2:".<br>Course outline :  |               |  |              |   |                                  |  |  |  |
|                      |                         |                                  | Acquire practical control theory used in the field and understand the application fields of control engineering.   |               |  |              |   |                                  |  |  |  |
| Style                |                         | Classes a conducti               | Course method :<br>Classes are offered in 2 credit hours (90 minutes) per week. The student will deepen their understanding by<br>conducting exercise guidance, confirmation tests, and assignment reports according to the progress of<br>learning.   |               |  |              |   |                                  |  |  |  |
|                      |                         | Exams (<br>Evaluate              | Grade evaluation method :<br>Exams (60%) + Confirmation tests (40%).<br>Evaluate the results of each of the two examinations equally. Items that can be brought in for the test will be<br>instructed each time. Those with poor grades will be retested and added so that the result of the regular test<br>will be a maximum of 60 points. Confirmation tests performed during class and learning outcomes outside<br>class hours (exercises for assignments, reports, etc.) are evaluated equally, and up to 40% is considered.<br>However, learning outcomes that have passed the submission deadline will be evaluated up to 30%. |               |  |              |   |                                  |  |  |  |
| Notice               |                         | Precaution<br>This is a          | Precautions on the enrollment :<br>This is a "class that requires study outside of class hours". Classes are offered for 15 hours per credit, but 30 credit hours are required in addition to this. Follow the instructions of your instructor for these studies.  |               |  |              |   |                                  |  |  |  |
|                      |                         |                                  | Course advice :<br>It requires knowledge about "control engineering", so review it.  |               |  |              |   |                                  |  |  |  |
|                      |                         | Engineer                         | Foundational subjects : Basic Electrical Controls (2nd year), Electronic and Information Circuits (4th), Control Engineering (5th)<br>Related subjects :   |               |  |              |   |                                  |  |  |  |
|                      |                         | Confirm                          | Attendance advice :<br>Confirm attendance at the beginning of class. Please note that you will be absent from school 3 times late. If<br>you decide that it will interfere with other people's attendance, you may be asked to leave.  |               |  |              |   |                                  |  |  |  |
| Course               | Plan                    |                                  |  |               |  | ance, y      |   |                                  |  |  |  |
| Course               |                         |                                  | Theme  |               |  | Goal         | c   |                                  |  |  |  |
| 1st<br>Semeste<br>r  | 1st<br>Quarter          | 1st                              | пепе   |               |  |              | 5   |                                  |  |  |  |
|                      |                         | 2nd                              |  |               |  |              |   |                                  |  |  |  |
|                      |                         | 2nd<br>3rd                       |  |               |  |              |   |                                  |  |  |  |
|                      |                         |                                  |  |               |  |              |   |                                  |  |  |  |
|                      |                         | 4th                              |  |               |  |              |   |                                  |  |  |  |
|                      |                         | 5th                              |  |               |  |              |   |                                  |  |  |  |
|                      |                         | 6th<br>7th                       |  |               |  |              |   |                                  |  |  |  |
|                      |                         | 7th                              |  |               |  |              |   |                                  |  |  |  |
|                      |                         | 8th                              |  |               |  |              |   |                                  |  |  |  |

|                            |                | 9th        |                                       |  |               |           |                    |       |
|----------------------------|----------------|------------|---------------------------------------|--|---------------|-----------|--------------------|-------|
|                            |                | 10th       |                                       |  |               |           |                    |       |
|                            |                | 11th       |                                       |  |               |           |                    |       |
|                            | 2nd<br>Quarter | 12th       |                                       |  |               |           |                    |       |
|                            |                | 13th       |                                       |  |               |           |                    |       |
|                            |                | 14th       |                                       |  |               |           |                    |       |
|                            |                | 15th       |                                       |  |               |           |                    |       |
|                            |                | 16th       |                                       |  |               |           |                    |       |
| 2nd                        |                | 1st        | Guidance                              |  |               |           |                    |       |
|                            |                | 2nd        | Basic form of PID control system      |  |               |           |                    |       |
|                            |                | 3rd        | Digital PID control                   | system                                       |               |           |                    |       |
|                            | 3rd            | 4th        | I-PD control syste                    | m, P-ID control s                            | system        |           |                    |       |
|                            | Quarter        | 5th        | 2 degrees of freed                    | om PID control s                             | system        |           |                    |       |
|                            |                | 6th        | PID parameter tur<br>Gain method)     | ning (Ziegler-Nich                           | ols' Ultimate |           |                    |       |
|                            |                | 7th        | PID parameter tur                     | ning (CHR metho                              | d)            |           |                    |       |
| Semeste                    |                | 8th        | 2nd semester mid                      | -term exam                                   |               |           |                    |       |
| r                          |                | 9th        | Return and commentary of exam answers |  |               |           |                    |       |
|                            |                | 10th       | Dynamic system and state equation     |  |               |           |                    |       |
|                            |                | 11th       | System model and                      | l linearization (1)                          | )             |           |                    |       |
|                            | 4th            | 12th       | System model and linearization (2)    |  |               |           |                    |       |
|                            | Quarter        | 13th       | System coordinate transformation (1)  |  |               |           |                    |       |
|                            |                |            | System coordinate transformation (2)  |  |               |           |                    |       |
|                            |                | 15th       | (2nd semester final exam)             |  |               |           |                    |       |
|                            |                | -          | Return and comm                       | entary of exam a                             | nswers        |           |                    |       |
| Evaluat                    | <u>ion Met</u> | hod and V  | Veight (%)                            | 1  | 1             |           |                    |       |
| E                          |                | kamination | Presentation                          | Mutual<br>Evaluations<br>between<br>students | Behavior      | Portfolio | Assignment<br>test | Total |
| Subtotal                   | 6              | )          | 0                                     | 0  | 0             | 0         | 40                 | 100   |
| Basic<br>Proficiency       |                |            | 0                                     | 0  | 0             | 0         | 0                  | 0     |
| Specialized<br>Proficiency |                | )          | 0                                     | 0  | 0             | 0         | 40                 | 100   |
| Cross Are<br>Proficienc    |                |            | 0                                     | 0  | 0             | 0         | 0                  | 0     |