| Anan College | | | Year 2024 | | | | ourse itle | Machine Dynamics 2 | | |
|---|--|--|--|--|--|-----------------------|--|--|--|--|
| Course : | Informat | ion | 1 | -1 | | l . | | | | |
| Course Co | | 1214C01 | | | Course Catego | ry : | Specialize | d / Compulsory | | |
| Class Format Lecture | | | | | | | Academic | Credit: 2 | | |
| | | | Mechanical Engineering | | Student Grade | | | | | |
| Term Second Se | | | | | Classes per We | ses per Week 後期:2 | | | | |
| Textbook Teaching | Matérials | | aku (CORONA) | | | | | | | |
| Instructor | | • | a Nariyuki | | | | | | | |
| 1. Unders 2. Able to terms of e 3. Able to displacem 4. Unders | explain the equations of express a ent by equ | derive equate types of votion. If motion, and analyze the pations of motions | vibration and to a the forced vibrate notion. | • | otion of mass, s ystem subjected | | • | ot systems by expressing them in ernal force and harmonic | | |
| Rubric | | | | | | | | 1 | | |
| | | | Ideal Level | Ideal Level | | Standard Level | | Minimum Level | | |
| Achievement 1 | | | Able to analyze the motion of complex-shaped objects, including rigid bodies, and dynamical systems composed of many objects. | | Able to derive the equations of motion for simple dynamical systems at the exercise level and analyze the motion of the system. | | amical e level | Able to derive the equations of motion for simple dynamical systems at the example level and analyze the motion of the system. | | |
| Achievement 2 | | | equations of n | derive and analyze the ons of motion for free on and identify the eters of the system from nental results. Able to derive the equinotion for free vibrat systems and explain a results. | | | on | motion for free vibration | | |
| Achievement 3 | | | motion for for systems and countries the relationship | correctly explain p between | Able to derive the equations of motion for forced vibration systems and analyze the motion of the system. | | ition | Able to derive the equations of motion for forced vibration systems. | | |
| Achievement 4 | | | of resonance a | oration prevention | Understand resonance phenomena and explain vario | | | Able to explain the basic application of various vibration prevention methods. | | |
| Assigne | d Depart | ment Ob | jectives | | | | | | | |
| 学習・教育 | 到達度目標 | ₹ В-3 学習・ | 教育到達度目標 [|)-1 | | | | | | |
| Teachin | g Metho | d | | | | | | | | |
| Outline related to is to maste | | | ynamics is one of the essential fields for designing machines, which includes a wide range of fields machines such as statics, dynamics, kinematics, vibration, and control. The objective of this course er the fundamentals of kinematics to vibration science while using the knowledge acquired in mechanics. | | | | | | | |
| Style solve the e Online ass contents o | | | d of each class, exercises will be provided as self-study assignments. Each student is required to exercises and submit them as a review. signments via manaba will be provided in advance of the class. Each student is required to check the of the next lesson in advance and answer the exercises. of class time + 60 hours of self-study] | | | | | | | |
| Notice | | are exped are plent vibration The portf | cted to review th y of exercises ot analysis through | ne fundamentals of her than the assign n independent stud | mechanics thor nments, and stu ly. | oughly l idents ai | before the re expecte | Il mechanics courses. Students be beginning of the course. There ed to master the methods of elf-study assignments)] and | | |
| Charact | eristics c | of Class / | Division in Le | earning | | | | | | |
| ☑ Active Learning | | | ☑ Aided by I | | ☑ Applicable to Remote Class | | te Class | ☐ Instructor Professionally Experienced | | |
| Course | Dlan | | | | | | | | | |
| Course | riali | - | Thoma | | | Goals | | | | |
| 2nd Semeste r | 3rd Quarter | 1 ot | Fheme Fundamentals of Mathematics for | undamentals of Dynamics I and Fundamentals of athematics for Machine Dynamics | | | Understand Newton's laws of motion and be able to model systems. Able to calculate ordinary differential equations and matrices. | | | |
| | | | Fundamentals of Rigid Body I | Dynamics of | Able to derive equations of motion for modeled systems and analyze simple systems. Able to calculate the moment of inertia of rigid bodies with relatively complex geometry. | | | | | |
| | | 3rd [| Dynamics of Rigi | namics of Rigid Body II | | | | Able to analyze the plane motion of a rigid body considering its moment of inertia. | | |

| | | 4th | Vibration | ion of single-degree-of-freedom system I | | | Able to analyze Maxwell's model and Voigt's model. Understand the function of springs and analyze the vibration of undamped single-degree-of-freedom systems. | | | | |
|----------------------------|----------------|----------------------|--|--|-----------|--|--|--|-------|--|--|
| | | 5th | Vibration of single-degree-of-freedom system II | | | | Able to analyze the motion of a physical pendulum. Understand the phenomenon of damped vibration and classify it by damping ratio. | | | | |
| | | 6th | Vibration of single-degree-of-freedom system III | | | | Understand the function of a dashpot and be able to analyze the vibration of a damped single-degree-of-freedom system. Understand logarithmic damping rate and be able to calculate the damping rate from damping waveforms. | | | | |
| | | 7th | Vibration of single-degree-of-freedom system IV and Forced Vibration I | | | | Able to analyze the vibration of single-degree-of- freedom system subjected to impact force. Analyze forced vibration due to harmonic external force and explain the resonance phenomenon. | | | | |
| | | 8th | Midterr | m examination | | | | | | | |
| | | 9th | Forced Vibration II | | | | Able to analyze by the half power method. Able to analyze forced vibration due to displacement input. | | | | |
| | | 10th | Vibration of two-degree-of-freedom systems | | | | Able to analyze free and forced vibration analysis of two-degree-of-freedom systems. | | | | |
| | | 11th | Vibrati | Vibration of continuous systems | | | | Understand modeling by partial differential equations for strings and be able to analyze the vibration of a continuum. | | | |
| | 4th Quarter | 12th | Vibration of Rotating Body I | | | | Understand rotational motion and be able to analyze vibrations due to critical velocity and disproportionality. | | | | |
| | | 13th | Vibration of Rotating Body II | | | | Understand the disproportionate amount of disproportion and be able to design the balancing design of rotating parts. | | | | |
| | | 14th | Prevention of Vibration I | | | | Able to explain the types and characteristics of vibration prevention methods. | | | | |
| | | 15th | Preven | tion of Vibration II | | Understand vibration insulation and be able to design dynamic absorbers. | | | | | |
| | | 16th | Reflection of final examination | | | | | | | | |
| Evaluation | n Meth | nod and | Weight | t (%) | | | | | | | |
| | | midterm / final exam | | quiz | portfolio | presentation / attitude | | other | Total | | |
| Subtotal | | 70 | | 0 | 30 | 0 | | 0 | 100 | | |
| Basic Proficiency | | 10 | | 0 | 0 | 0 | | 0 | 10 | | |
| Specialized Proficiency | | 60 | | 0 | 30 | 0 | | 0 | 90 | | |
| Cross Area Proficiency | | 0 | | 0 | 0 | 0 | | 0 | 0 | | |