Tsuyama Coll		College	ege Year 202			20			Course Advanced Controls			
Course 1									Title	Engine	eering	
Course Co		0149					Course Cated	1017/	Specializ	od / Flac	tivo	
Class Forn		Lecture	۵				Credits	jury	Specialized / Elective Academic Credit: 2			
Department		Departi Techno	Department of Integrated Science and Technology Communication and				Student Grade		5th			
•				System Pro	gram							
Term Toythook	Year-ro					Classes per Week 1						
Teaching I	extbook and/or eaching Materials Textbooks: "Wakariyasui Gendai Seigyo Riron" Mori, (Morikita Syuppan) Structor YAGI Hideyuki											
Course (-	ildeyüki									
Learning p	ourposes :		olied cor	ncepts rela	ted to	automatic co	ontrol theory.					
Course Ob 1. To unde 2. To unde	ojectives : erstand PI erstand m	D control odern con	theory. itrol the	eory.								
Rubric												
		Exc	cellent			Good		Acceptable			Not acceptable	
Achievement 1		PIC	The student can apply PID control theory to complex problems.		The student can understand the theory of PID control theory.		The student can understand the basic theory of PID control			The student will not try to understand the basic theory of PID control.		
Achievement 2		lmo	The student can apply modern control theory to complex problems.				The student can understand the basic theory of modern control.			The student will not try to understand the basic theory of modern control.		
Assigned	d Depar	•					,					
Teaching												
Outline		Relation This cla Relation The ma Course Acquire Classes conduct learning Grade e Exams	Required, Elective, etc.: Élective subjects Foundational academic disciplines: Engineering / Electrical and electronic engineering / Control and system engineering Relationship with Educational Objectives: This class is equivalent to "(2) Acquire basic science and technical knowledge". Relationship with JABEE programs: The main goals of learning / education in this class are "(A), A-2:". Course outline: Acquire practical control theory used in the field and understand the application fields of control engineering. Course method: Classes are offered in 2 credit hours (90 minutes) per week. The student will deepen their understanding by conducting exercise guidance, confirmation tests, and assignment reports according to the progress of learning. Grade evaluation method: Exams (60%) + Confirmation tests (40%).									
		Evaluat instruct will be class he Howeve	Evaluate the results of each of the two examinations equally. Items that can be brought in for the test will be instructed each time. Those with poor grades will be retested and added so that the result of the regular test will be a maximum of 60 points. Confirmation tests performed during class and learning outcomes outside class hours (exercises for assignments, reports, etc.) are evaluated equally, and up to 40% is considered. However, learning outcomes that have passed the submission deadline will be evaluated up to 30%. Precautions on the enrollment:									
Notice		Credit h Course It requi Founda Enginee Related Attenda Confirm	This is a "class that requires study outside of class hours". Classes are offered for 15 hours per credit, but 30 credit hours are required in addition to this. Follow the instructions of your instructor for these studies. Course advice: It requires knowledge about "control engineering", so review it. Foundational subjects: Basic Electrical Controls (2nd year), Electronic and Information Circuits (4th), Control Engineering (5th) Related subjects: Attendance advice: Confirm attendance at the beginning of class. Please note that you will be absent from school 3 times late. If you decide that it will interfere with other people's attendance, you may be asked to leave.									
Course I	Plan	you ded	cide tha	it it will int	erfere	with other p	eople's attend	ance, y	ou may be	asked to	leave.	
			Them	e				Goal	S			
1st Semeste r		1st										
	1st Quarter	2nd										
		3rd				·						
		4th				· · ·	· · · · · · · · · · · · · · · · · · ·					
		5th				· ·						
		6th				· · · · · · · · · · · · · · · · · · ·	· · · · · · · · · · · · · · · · · · ·					
		7th										
		8th										

		9th						
		10th						
		11th						
	2nd	12th						
	Quarte							
		14th						
		15th						
		16th						
		1st	Guidance					
		2nd	Basic form of PID	control system				
		3rd	Digital PID contro					
		4th	I-PD control syste		system			
	3rd Quarte	r 5th	2 degrees of freed	lom PID control s	system			
	Quarte	6th	PID parameter tur Gain method)	ning (Ziegler-Nich	nols' Ultimate			
		7th	PID parameter tur	ning (CHR metho	d)			
2nd Semeste		8th	2nd semester mid	-term exam				
r		9th	Return and comm	entary of exam a	nswers			
		10th	Dynamic system a	and state equatio	n			
		11th	System model and	d linearization (1))			
	4th	12th	System model and	d linearization (2))			
	Quarte	r 13th	System coordinate	e transformation	(1)			
		14th	System coordinate	e transformation	(2)			
		15th	(2nd semester fin	al exam)				
		16th	Return and comm	entary of exam a	inswers			
Evaluat	ion Me	thod and	Weight (%)					
		Examination	Presentation	Mutual Evaluations between students	Behavior	Portfolio	Assignment test	Total
Subtotal		50	0	0	0	0	40	100
Basic Proficiency)	0	0	0	0	0	0
Specialized Proficiency		50	0	0	0	0	40	100
Cross Area Proficiency)	0	0	0	0	0	0